Green Means Go Ahead and Cite That

A Citation Activity for Undergraduate Engineering Students

**Each citation below represents a resource you may use during your research projects. Assign one of the three designations below to each resource.**

  **Green -** a credible resource that can always be cited

**Yellow -** a resource that can be credible but needs to be assessed on a case-by-case basis

**Red -** a resource that is not credible and should not be cited under any circumstances

**Once you have assigned a designation, explain why you made that decision in the text box attached to the citation.**

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| \_\_\_\_\_\_ B.-Y. Shih, C.-Y. Chen, and W.-C. Chou, “RETRACTED: Obstacle avoidance using a path correction method for autonomous control of a biped intelligent robot,” J. Vib. Control, vol. 17, no. 10, pp. 1567–1573, Nov. 2010. (2) |
| \_\_\_\_\_\_ J. Capp and B. Litkouhi, “The Crash-Proof Car,” IEEE Spectrum: Technology, Engineering, and Science News, 30-Apr-2014. [Online]. Available: https://spectrum.ieee.org/ [Accessed: 01-Nov-2017]. (3) |
| \_\_\_\_\_\_ E18 Committee, “Test Method for Sensory Evaluation of Low Heat Chilies,” ASTM International, West Conshohocken, PA, Feb. 2017. (4) |
| \_\_\_\_\_\_ A. B. Howard and T. K. Marks, “Visual SLAM Using Variance Grid Maps,” Jet Propulsion Lab., California Inst. of Tech.; Pasadena, CA, United States, 20110003003, Jan. 2011. (6) |
| \_\_\_\_\_\_ Samsung Electronics Co. Ltd , “Simultaneous Localization And Map Building Method And Medium For Moving Robot,” U.S. Patent 8331652 B52 Dec 11, 2012. (5) |
| \_\_\_\_\_\_ J. Melo and A. Matos, “Survey on advances on terrain based navigation for autonomous underwater vehicles,” Ocean Eng., vol. 139, no. Supplement C, pp. 250–264, Jul. 2017. (7) |
| \_\_\_\_\_\_ D. Nemec, M. Hrubos, M. Gregor, and E. Bubenikova, “Visual Localization and Identification of Vehicles Inside a Parking House,” Procedia Engineering, vol. 192, no. Supplement C, pp. 632–637, Jan. 2017. (8) |
| \_\_\_\_\_\_ K. Boikos and C. S. Bouganis, “A high-performance system-on-chip architecture for direct tracking for SLAM,” in 2017 27th International Conference on Field Programmable Logic and Applications (FPL), 2017, pp. 1–7. (9) |
| \_\_\_\_\_\_ R. Kopper, S. Lampotang, and A. Robb, “Exploring Agent Physicality and Social Presence for Medical Team Training.” [Online]. Available: https://www.academia.edu/ [Accessed: 16-Nov-2017]. (10) |
| \_\_\_\_\_\_ L. Hall, “Monocular SLAM for Smart SPHERES,” 18-Dec-2014. [Online]. Available: http://www.nasa.gov/. [Accessed: 16-Nov-2017]. (11) |

Explain why you chose {Citation} as Green.

Explain why you chose {Citation} as Yellow.

Explain why you chose (Citation} as Red.

**Each resource type below is one you may use during your research projects. Assign one of the three designations below to each resource:** **Green -** a credible resource that can always be cited

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| Technical Report (1) |
| Trade Publication (2) |
| Journal Article, peer-reviewed (3) |
| Standard (4) |
| Patent (5) |
| Conference Proceedings (6) |
| Article from Academia.edu, ResearchGate.net, or similar site (7) |
| Journal article, retracted (8) |
| .gov webpage (9) |

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Explain why you chose {Resource Type} as Yellow.

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Explain any thoughts, comments, or questions on this exercise.